Signals and Systems - Chapter 5

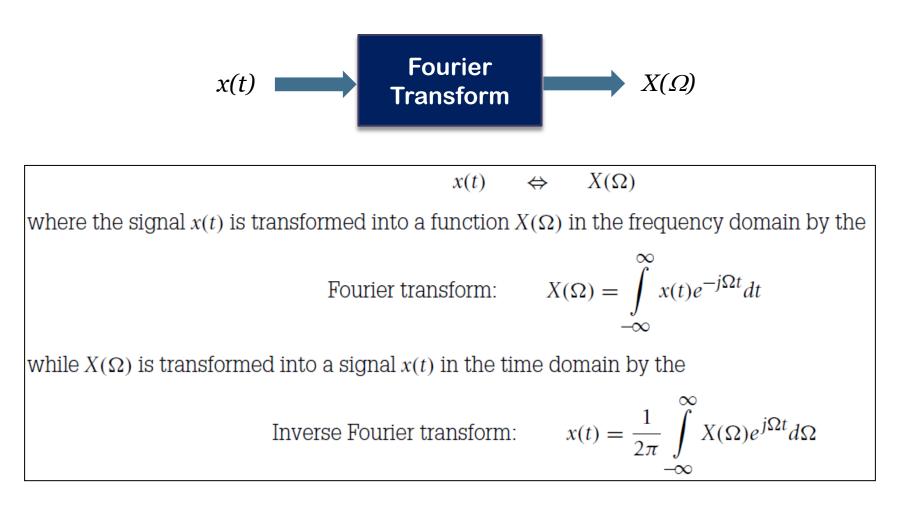
The Fourier Transform

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Overview of Chapter 0

- Importance of the theory of signals and systems
- Mathematical preliminaries
- Matlab introduction (section)

Fourier Transform Definition



Existence of Fourier Transform

- The Fourier transform of a signal *x*(*t*) exists (i.e., we can calculate its Fourier transform via this integral) provided that:
 - x(t) is absolutely integrable or the area under |x(t)| is finite
 - x(t) has only a finite number of discontinuites as well as maxima and minima
- These conditions are "<u>sufficient</u>" not "<u>necessary</u>"

Fourier Transforms from Laplace Transforms

 If the region of convergence (ROC) of the Laplace transform *X*(*s*) contains the *j*Ω axis, so that *X*(*s*) can be defined for *s* = D *j*Ω, then:

$$\mathcal{F}[x(t)] = \mathcal{L}[x(t)]|_{s=j\Omega} = \int_{-\infty}^{\infty} x(t)e^{-j\Omega t}dt$$
$$= X(s)|_{s=j\Omega}$$

Fourier Transforms from Laplace Transforms - Example

• Discuss whether it is possible to obtain the Fourier transform of the following signals using their Laplace transforms:

(a) $x_1(t) = u(t)$ (b) $x_2(t) = e^{-2t}u(t)$

- (a) The Laplace transform of $x_1(t)$ is $X_1(s) = 1/s$ with a region of convergence corresponding to the open right *s*-plane, or ROC = { $s = \sigma + j\Omega : \sigma > 0, -\infty < \Omega < \infty$ }, which does not include the $j\Omega$ axis, so the Laplace transform cannot be used to find the Fourier transform of $x_1(t)$.
- (b) The signal $x_2(t)$ has as Laplace transform $X_2(s) = 1/(s+2)$ with a region of convergence ROC = { $s = \sigma + j\Omega : \sigma > -2, -\infty < \Omega < \infty$ } containing the $j\Omega$ axis. Then the Fourier transform of $x_2(t)$ is

$$X_2(\Omega) = \frac{1}{s+2} \Big|_{s=j\Omega} = \frac{1}{j\Omega+2}$$

Table 5.2 Fourier Transform Pairs			
	Function of Time	Function of Ω	
1	$\delta(t)$	1	
2	$\delta(t-\tau)$	$e^{-j\Omega\tau}$	
3	u(t)	$\frac{1}{i\Omega} + \pi \delta(\Omega)$	
4	u(-t)	$\frac{-1}{i\Omega} + \pi \delta(\Omega)$	
5	sgn(t) = 2[u(t) - 0.5]	$\frac{2}{i\Omega}$	
6	$A, -\infty < t < \infty$	$2\pi A\delta(\Omega)$	
7	$Ae^{-at}u(t), \ a > 0$	$\frac{A}{j\Omega+a}$	
8	$Ate^{-at}u(t), a > 0$	$\frac{A}{(j\Omega+a)^2}$	
9	$e^{-a t }, \ a > 0$	$\frac{2a}{a^2+\Omega^2}$	
10	$\cos(\Omega_0 t), -\infty < t < \infty$	$\pi \left[\delta(\Omega - \Omega_0) + \delta(\Omega + \Omega_0) \right]$	
11	$\sin(\Omega_0 t), -\infty < t < \infty$	$-j\pi \left[\delta(\Omega-\Omega_0) - \delta(\Omega+\Omega_0) \right]$	
12	$A[u(t+\tau)-u(t-\tau)],\ \tau>0$	$2A\tau \frac{\sin(\Omega\tau)}{\Omega\tau}$	
13	$\frac{\sin(\Omega_0 t)}{\pi t}$	$u(\Omega+\Omega_0)-u(\Omega-\Omega_0)$	
14	$x(t)\cos(\Omega_0 t)$	$0.5[X(\Omega - \Omega_0) + X(\Omega + \Omega_0)]$	

Linearity

- Fourier transform is a linear operator
- Superposition holds

If $\mathcal{F}[x(t)] = X(\Omega)$ and $\mathcal{F}[y(t)] = Y(\Omega)$, for constants α and β , we have that $\mathcal{F}[\alpha x(t) + \beta y(t)] = \alpha \mathcal{F}[x(t)] + \beta \mathcal{F}[y(t)]$ $= \alpha X(\Omega) + \beta Y(\Omega)$

Inverse Proportionality of Time and Frequency

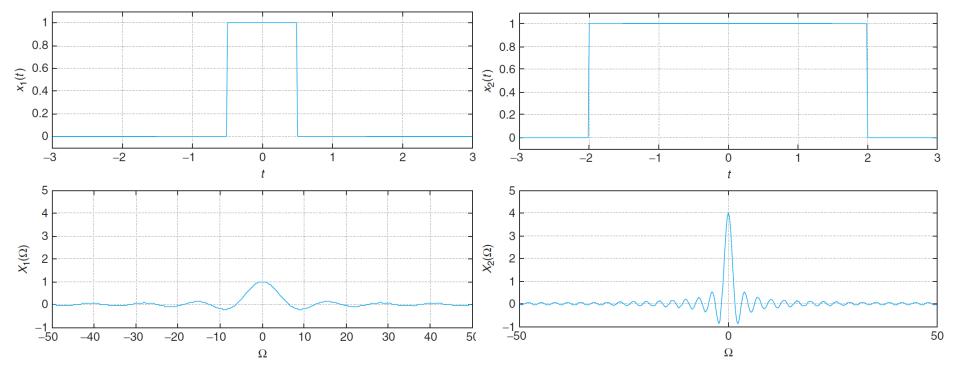
- Support of $X(\Omega)$ is inversely proportional to support of x(t)
- If *x*(*t*) has a Fourier transform *X*(Ω) and *α*≠0 is a real number, then *x*(*αt*) is:
 - Contracted ($\alpha > 1$),
 - Contracted and reflected ($\alpha < -1$),
 - Expanded $(0 < \alpha < 1)$,
 - Expanded and reflected $(-1 < \alpha < 0)$, or
 - Simply reflected ($\alpha = -1$)

• Then,

$$x(\alpha t) \quad \Leftrightarrow \quad \frac{1}{|\alpha|} X\left(\frac{\Omega}{\alpha}\right)$$

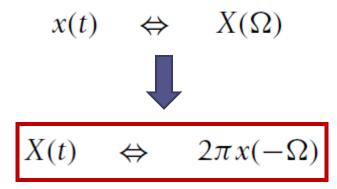
Inverse Proportionality of Time and Frequency - Example

- Fourier transform of 2 pulses of different width
 - 4-times wider pulse have 4-times narrower Fourier transform

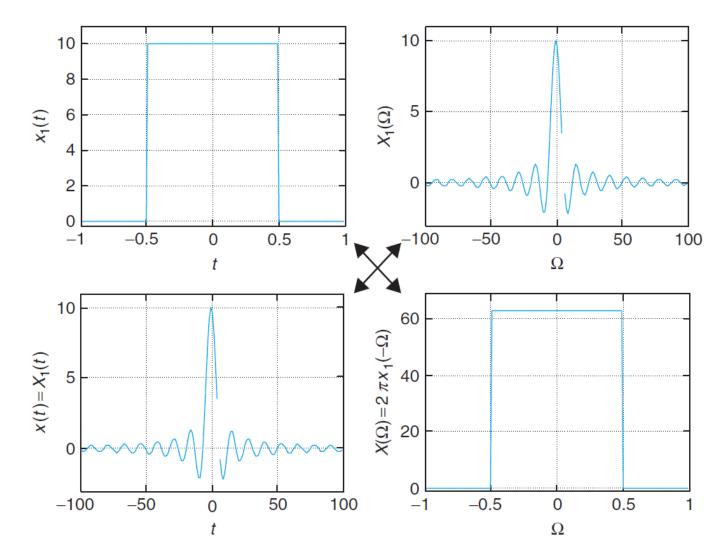


Duality

- By interchanging the frequency and the time variables in the definitions of the direct and the inverse Fourier transform similar equations are obtained
- Thus, the direct and the inverse Fourier transforms are <u>dual</u>



Duality: Example



Signal Modulation

- Frequency shift: If $X(\Omega)$ is the Fourier transform of x(t), then we have the pair $x(t)e^{j\Omega_0 t} \Leftrightarrow X(\Omega \Omega_0)$
- Modulation: The Fourier transform of the modulated signal

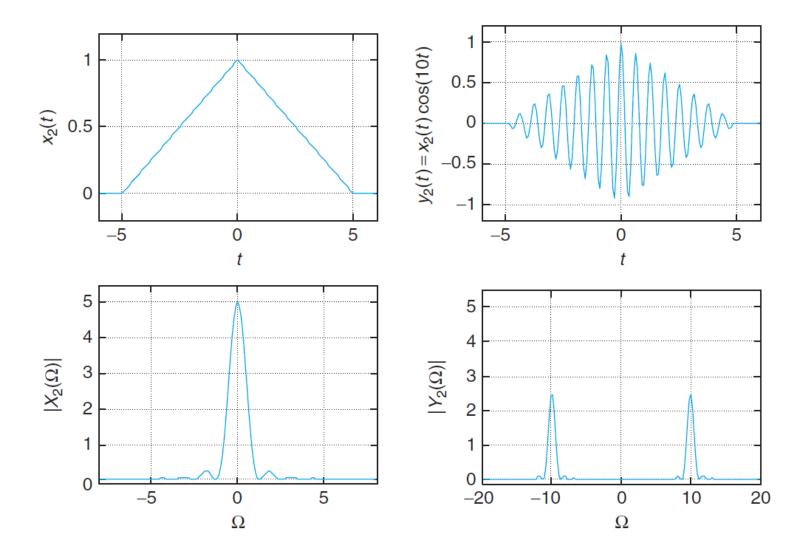
 $x(t)\cos(\Omega_0 t)$

is given by

 $0.5 \left[X(\Omega - \Omega_0) + X(\Omega + \Omega_0) \right]$

That is, $X(\Omega)$ is shifted to frequencies Ω_0 and $-\Omega_0$, and multiplied by 0.5.

Signal Modulation: Example



Fourier Transform of Periodic Signals

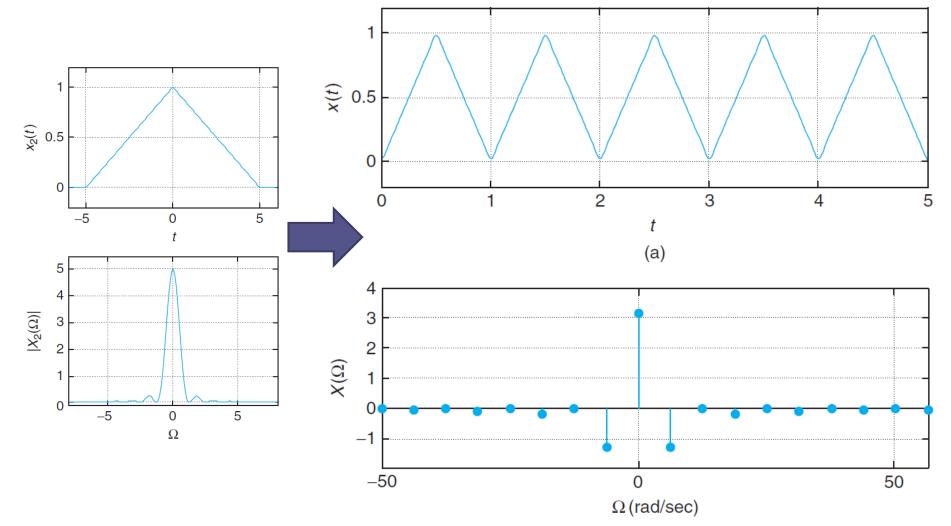
For a periodic signal x(t) of period T_0 , we have the Fourier pair

$$x(t) = \sum_{k} X_{k} e^{jk\Omega_{0}t} \quad \Leftrightarrow \quad X(\Omega) = \sum_{k} 2\pi X_{k} \delta(\Omega - k\Omega_{0})$$

obtained by representing x(t) by its Fourier series.

- Periodic Signals are represented by Sampled Fourier transform
- Sampled Signals are representing by Periodic Fourier Transform (from duality)

Fourier Transform of Periodic Signals: Example



Parseval's Energy Conservation

For a finite-energy signal x(t) with Fourier transform $X(\Omega)$, its energy is conserved when going from the time to the frequency domain, or

$$E_x = \int_{-\infty}^{\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{\infty} |X(\Omega)|^2 d\Omega$$
(5.15)

Thus, $|X(\Omega)|^2$ is an energy density indicating the amount of energy at each of the frequencies Ω . The plot $|X(\Omega)|^2$ versus Ω is called the energy spectrum of x(t), and it displays how the energy of the signal is distributed over frequency.

• Energy in Time Domain = Energy in Frequency Domain

Symmetry of Spectral Representations

If $X(\Omega)$ is the Fourier transform of a real-valued signal x(t), periodic or aperiodic, the magnitude $|X(\Omega)|$ is an even function of Ω :

$$|X(\Omega)| = |X(-\Omega)| \tag{5.16}$$

and the phase $\angle X(\Omega)$ is an odd function of Ω :

$$\angle X(\Omega) = -\angle X(-\Omega) \tag{5.17}$$

We then have:

Magnitude spectrum:	$ X(\Omega) $ versus Ω
Phase spectrum:	$\angle X(\Omega)$ versus Ω
Energy/power spectrum:	$ X(\Omega) ^2$ versus Ω

 Clearly, if the signal is complex, the above symmetry will NOT hold

Convolution and Filtering

If the input x(t) (periodic or aperiodic) to a stable LTI system has a Fourier transform $X(\Omega)$, and the system has a frequency response $H(j\Omega) = \mathcal{F}[h(t)]$ where h(t) is the impulse response of the system, the output of the LTI system is the convolution integral y(t) = (x * h)(t), with Fourier transform

$$Y(\Omega) = X(\Omega) H(j\Omega)$$

(5.18)

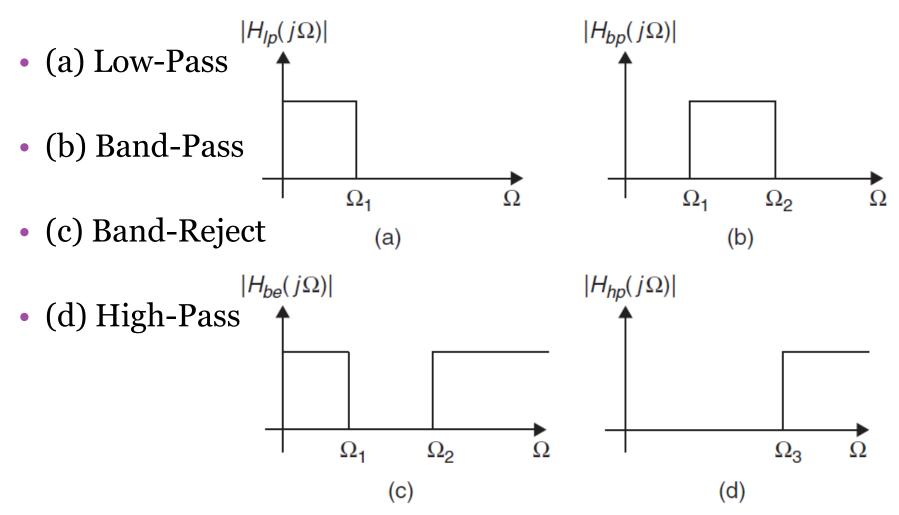
Relation between transfer function and frequency response:

Basics of Filtering

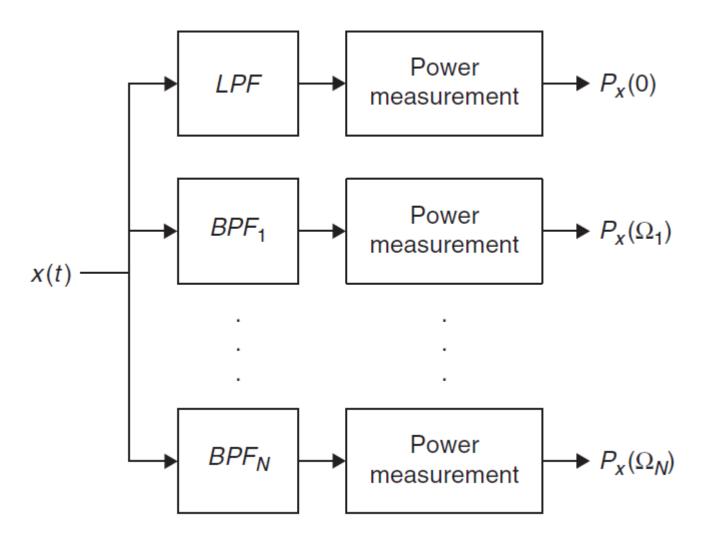
 The filter design consists in finding a transfer function *H*(*s*)= *B*(*s*)=*A*(*s*) that satisfies certain specifications that will allow getting rid of the noise. Such specifications are typically given in the frequency domain.

 $Y(\Omega) = H(j\Omega)X(\Omega)$





Spectrum Analyzer



Time Shifting Property

If x(t) has a Fourier transform $X(\Omega)$, then $x(t - t_0) \Leftrightarrow X(\Omega)e^{-j\Omega t_0}$ $x(t + t_0) \Leftrightarrow X(\Omega)e^{j\Omega t_0}$

• Example: $x(t) = A[\delta(t - \tau) + \delta(t + \tau)]$

 $X(\Omega) = A [1e^{-j\Omega\tau} + 1e^{j\Omega\tau}]$

Differentiation and Integration

If x(t), $-\infty < t < \infty$, has a Fourier transform $X(\Omega)$, then $\frac{d^{N}x(t)}{dt^{N}} \quad \Leftrightarrow \quad (j\Omega)^{N}X(\Omega)$ $\int_{0}^{t} x(\sigma)d\sigma \quad \Leftrightarrow \quad \frac{X(\Omega)}{j\Omega} + \pi X(0)\delta(\Omega)$ where $X(0) = \int x(t)dt$

Table 5.1 Basic Properties of the Fourier Transform					
	Time Domain	Frequency Domain			
Signals and constants Linearity Expansion/contraction in time Reflection Parseval's energy relation Duality Time differentiation Frequency differentiation Integration Time shifting Frequency shifting	$\begin{split} & x(t), y(t), z(t), \alpha, \beta \\ & \alpha x(t) + \beta y(t) \\ & x(\alpha t), \alpha \neq 0 \\ & x(-t) \\ & E_x = \int_{-\infty}^{\infty} x(t) ^2 dt \\ & X(t) \\ & \frac{d^n x(t)}{dt^n}, n \geq 1, \text{ integer} \\ & -jtx(t) \\ & \int_{-\infty}^t x(t') dt' \\ & x(t - \alpha) \\ & e^{j\Omega_0 t} x(t) \end{split}$	$\begin{split} X(\Omega), Y(\Omega), Z(\Omega) \\ \alpha X(\Omega) + \beta Y(\Omega) \\ \frac{1}{ \alpha } X\left(\frac{\Omega}{\alpha}\right) \\ X(-\Omega) \\ E_x &= \frac{1}{2\pi} \int_{-\infty}^{\infty} X(\Omega) ^2 d\Omega \\ 2\pi x(-\Omega) \\ (j\Omega)^n X(\Omega) \\ \frac{dX(\Omega)}{d\Omega} \\ \frac{X(\Omega)}{j\Omega} + \pi X(0)\delta(\Omega) \\ e^{-j\alpha\Omega} X(\Omega) \\ X(\Omega - \Omega_0) \end{split}$			
Modulation Periodic signals Symmetry Convolution in time Windowing/multiplication Cosine transform Sine transform	$x(t) \cos(\Omega_c t)$ $x(t) = \sum_k X_k e^{jk\Omega_0 t}$ x(t) real z(t) = [x * y](t) x(t)y(t) x(t) even x(t) odd	$\begin{array}{l} 0.5[X(\Omega - \Omega_c) + X(\Omega + \Omega_c)] \\ X(\Omega) &= \sum_k 2\pi X_k \delta(\Omega - k\Omega_0) \\ X(\Omega) &= X(-\Omega) \\ \angle X(\Omega) &= -\angle X(-\Omega) \\ Z(\Omega) &= X(\Omega)Y(\Omega) \\ \frac{1}{2\pi}[X * Y](\Omega) \\ X(\Omega) &= \int_{-\infty}^{\infty} x(t) \cos(\Omega t) dt, \text{ real} \\ X(\Omega) &= -j \int_{-\infty}^{\infty} x(t) \sin(\Omega t) dt, \text{ imaginary} \end{array}$			

Problem Assignments

- Problems: 5.4, 5.5, 5.6, 5.18, 5.20, 5.23
- Partial Solutions available from the student section of the textbook web site