## PART I. Choose the best answer for each of the following questions (2 points each)

- 1. The net magnetization refers to
  - a) The remaining magnetization after T2\* decay.
  - b) The difference between spins pointing with B0 and those pointing against B0
  - c) The magnetization in the transverse plane at equilibrium.
- 2. As the static magnetic field becomes higher, the MR signal from is expected to,
  - a) Increase quadratically
  - b) Decrease linearly
  - c) Increase linearly
- 3. The tipped magnetization vector under the laboratory frame of reference appears,
  - a) Precessing around z-axis at the Larmor frequency
    - b) Stationary
  - c) Rotating at the Larmor frequency.
- 4. In order to change the slice position of the RF pulse,
  - a) Change the pulse modulation frequency
  - b) Change the slice selection gradient position
  - c) Change the position of the patient
- 5. In order to change the slice thickness,
  - a) Change the slice amplitude
  - b) Change the envelope at the same bandwidth
  - c) Change the slice selection gradient
- 6. The rate at which the measured signal in the transverse plan disappears is a function of,
  - a) T1
  - b) T2
  - c) T2\*
- 7. The rate at which the inverted magnetization in inversion recovery sequences relaxes depends on,
  - a) T1
  - b) T2
  - c) T2\*
- 8. The signal decays fast in free induction decay because of,
  - a) Spin-spin relaxation
  - b) Spin dephasing
  - c) Spin lattice relaxation
- 9. The signal at time TE in a spin echo pulse sequence depends on,
  - a) T1
  - b) T2
  - c) T2\*

- 10. To measure T1, we usually use,
  - a) Inversion recovery pulse sequence
  - b) Gradient echo pulse sequence
  - c) Spin echo pulse sequence
- 11. The k-space represents,
  - a) The MR image space
  - b) The space where k-space trajectories are designed.
  - c) The Fourier domain of the image
- 12. The FOV in the read-out direction depends on,
  - a) Sampling bandwidth
  - b) Sampling duration
  - c) Sampling dynamic range
- 13. The FOV in the phase encoding direction depends mainly on,
  - a) Number of phase encoding steps
  - b) Phase encoding step size
  - c) Matrix size in the phase encoding direction
- 14. To increase the resolution in the read-out direction at the same FOV, one can,
  - a) Increase the k-space sampling bandwidth in the read-out direction
  - b) Increase the k-space coverage in the read-out direction
  - c) Increase the number of phase encoding steps in the read-out direction
- 15. To increase the FOV in the read-out direction without affecting the SNR, we can,
  - a) Use the same sampling BW with lower read-out gradient
  - b) Use the same sampling BW with higher read-out gradient
  - c) Use a higher bandwidth with the same read-out gradient
- 16. Magnetic resonance spectroscopy can be used for,
  - a) Mapping concentration of different metabolites in the human body noninvasively
  - b) Mapping concentration of different nuclei in the human body noninvasively
  - c) Mapping magnetic field inhomogeneity in PPM scale inside the magnet
- 17. Quenching means,
  - a) The magnet is being turned off after scanning a patient
  - b) The magnet is low on cryogenic agent
  - c) The magnet is abruptly and catastrophically losing magnetic field strength
- 18. MRA based on TOF can be used to detect,
  - a) Mapping blood velocity inside vessels
  - b) Mapping blood pressure inside vessels
  - c) Mapping vessel anatomy
- 19. Computed tomography refers to,
  - a) Computing images from their k-space data
  - b) Computing images from their spatial domain information
  - c) Computing sectional images from projection data

- 20. The problem of SPECT imaging is more difficult because,
  - a) The attenuation as well as the source location are not known
  - b) The incident x-ray energy is not known
  - c) The emitted photons are not well-defined in wavelength
- 21. The image of SPECT is composed of,
  - a) A map of the attenuation of the body
  - b) A map of the photon source intensity inside the body
  - c) A map of the positron source intensity inside the body
- 22. The T1-weighted MR image maps,
  - a) Both spin density and T1 inside the body
  - b) Only T1 values inside the body
  - c) Only spin density inside the body
- 23. The problem of PET reconstruction is solved using,
  - a) Reconstruction from projections
  - b) Fourier transform
  - c) Time-delay detector
- 24. Calculate the cardiac output given the following data:  $O_2$  consumption 200 ml/min, arterial  $O_2$  content 0.2 ml/ml, and venous  $O_2$  content 0.15 ml/ml.
  - a) 3 liters/min
  - b) 4 liters/min
  - c) 5 liters/min
- 25. In the rapid-injection indicator-dilution method,
  - a) The indicator concentration is measured at steady state
  - b) The indicator concentration curve is measured with time and integrated
  - c) The indicator concentration is measured right following the rapid injection
- 26. The thermodilution method relies on,
  - a) Injecting a cold indicator and measuring temperature change to compute flow
  - b) Measuring flow based on normal body temperature
  - c) Injecting a dye and measuring its concentration in the blood to compute flow
- 27. DC flowmeters suffer from,
  - a) Their signal is weak and hardly can be detected
  - b) Their signal has similar frequency range to that of ECG
  - c) They cannot measure AC components in the flow signal
- 28. Plethysmographs measure,
  - a) Change in flow rate
  - b) Change in heart rate
  - c) Change in volume
- 29. Ventricular fibrillation occurs when the current in the patient is in the range,
  - a) Approximately 10-100mA
  - b) Approximately 100mA-1A.
  - c) Approximately 1-6A

- 30. Suitable current range for defibrillators is between,
  - a) 1A-6A
  - b) 100mA-1A
  - c) 10mA-100mA

31. Microshock is defined as,

- a) The situation when a small current induces perception of electricity
- b) The situation when an electrical shock is applied from a defibrillator to revive a patient
- c) The situation when small currents from invasive devices induce ventricular fibrillation
- 32. Equipment isolation is usually done using,
  - a) Capacitive or optical isolation barrier
  - b) Circuit breakers
  - c) Isolation transformers
- 33. For a multi-slice imaging sequence with parameters given as: slice thickness: 5mm, flip angle: 60°, matrix size: 256×128, FOV: 20cm×20cm, NEX: 2, and TR/TE: 500/24, the ratio of acquisition time to acquire 25 slices to that of acquiring 20 slices using this sequence is,
  - a) 1.
  - b) 1.25.
  - c) 2.

34. A material that is chemically shifted from water by 100ppm has a different resonance frequency at 4T from that of water by approximately,

- a) 17 kHz.
- b) 4 kHz.
- c) 6.4 kHz.

35. Shimming coils are used for,

- a) Protecting the patient from fringe magnetic fields.
- b) Implementing the magnetic field gradients.
- c) Improving the uniformity of the B0 field.

36. The total acquisition time for a 3-D Fourier acquisition of a volume of matrix size 128×128×256 with TR/TE: 100/15ms is approximately,

- a) 14 minutes.
- b) 27 minutes.
- c) 54 minutes.

37. For a volumetric acquisition, doubling the number of phase encoding steps in the  $k_y$  direction without changing any other acquisition parameters results in,

- a) Lower SNR by a factor of  $\sqrt{2}$ .
- b) Higher SNR by a factor of  $\sqrt{2}$ .
- c) The same SNR.

38. For MRA based on phase contrast, when a volume of 128×128×128 is to be acquired in a multi-slice fashion, the minimum number of RF pulses to be used is,

- a) 128×128×2.
- b) 128×128.
- c) 128×128/2.

39. In T1-weighted imaging, structures with short T1 appear,

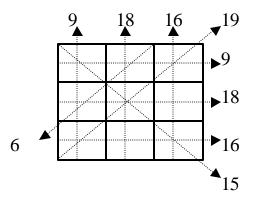
- a) Darker.
- b) Brighter.
- c) The same as other structures.
- 40. In T2-weighted imaging, structures with long T2 appear,
  - a) Darker.
  - b) Brighter.
  - c) The same as other structures.

## PART II. Answer the following with either True (T) or False (F) (1 point each),

- 1. DSR refers to a method for fast acquisition of SPECT data.
- 2. With 4T magnets, RF pulses are usually modulated with frequencies around 170MHz.
- 3. Acquisition time may vary with both TR and TE.
- 4. The different generations in CT vary in the geometry and numbers of sources and detectors.
- 5. Phase encoding can be theoretically used to encode any number of dimensions.
- 6. Increasing the number of phase encoding steps with the same step size reduces SNR.
- 7. PET relies on detecting and mapping positrons emerging from the object.
- 8. Patient isolation can be done only using isolated power to the equipment and proper Earthing.
- 9. Threshold of perception current denotes the current at which the patient is in danger.
- 10. Fick technique can be used to measure cardiac output.

**PART III**. Draw a properly labeled fat-nulling magnetic resonance imaging sequence and draw a clear diagram of its k-space trajectory. (**5 points**)

**PART IV.** Solve the following reconstruction problem using ART (5 points)



**BEST OF LUCK**